#### CSC212 Data Structure



#### Lecture 21 Recursive Sorting, Heapsort & STL Quicksort

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# Topics

Recursive Sorting Algorithms Divide and Conquer technique □ An O(NlogN) Sorting Alg. using a Heap □ making use of the heap properties □ STL Sorting Functions □ C++ sort function Original C version of qsort

#### The Divide-and-Conquer Technique

- □ Basic Idea:
  - □ If the problem is small, simply solve it.
  - □ Otherwise,
    - divide the problem into two smaller sub-problems, each of which is about half of the original problem
    - □ **Solve** each sub-problem, and then
    - **Combine** the solutions of the sub-problems

#### The Divide-and-Conquer Sorting Paradigm

- Divide the elements to be sorted into two groups of (almost) equal size
- 2. Sort each of these smaller groups of elements (by recursive calls)
- 3. Combine the two sorted groups into one large sorted list

# Mergesort void mer

#### void mergesort(int data[], size\_t n)

Divide the array in the middle

 Sort the two half-arrays by recursion
 Merge the two halves

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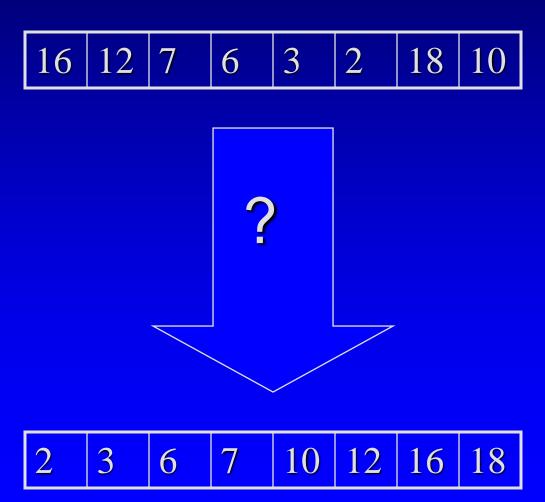
size\_t n1; // Size of the first subarray
size\_t n2; // Size of the second subarray

if (n > 1)
{
 // Compute sizes of the subarrays.
 n1 = n / 2;
 n2 = n - n1;

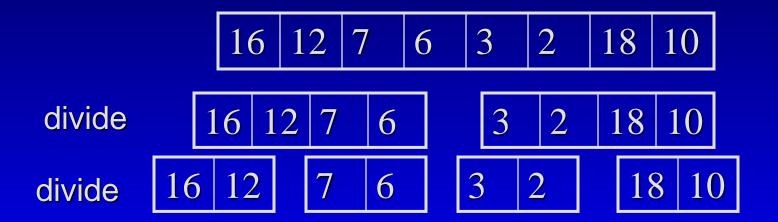
// Sort from data[0] through data[n1-1]
mergesort(data, n1);
// Sort from data[n1] to the end
mergesort((data + n1), n2);

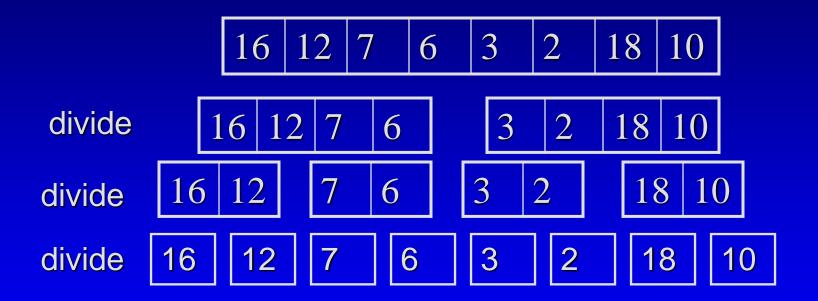
// Merge the two sorted halves. merge(data, n1, n2);

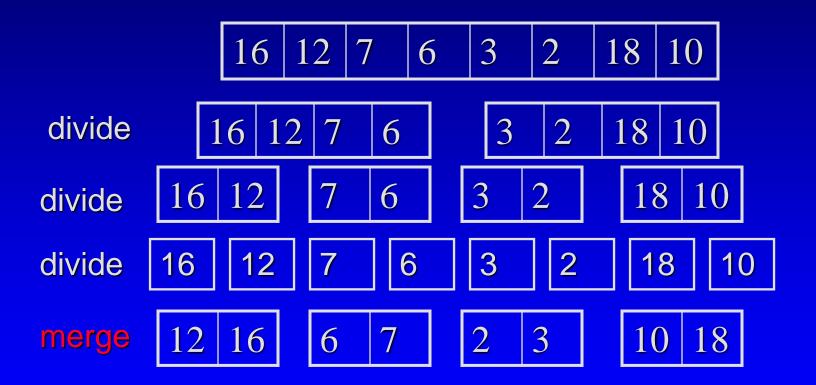
# 16 12 7 6 3 2 18 10 [0] [1] [2] [3] [4] [5] [6] [7]

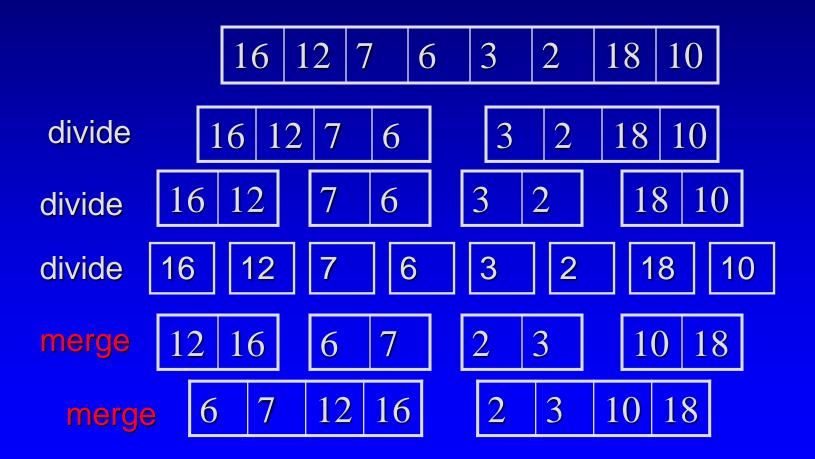








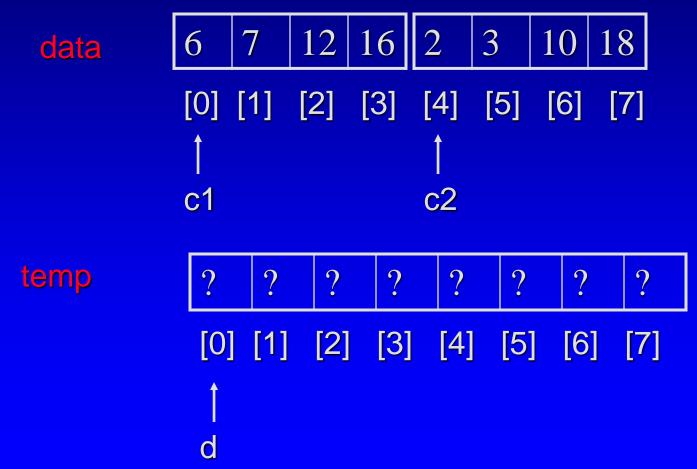


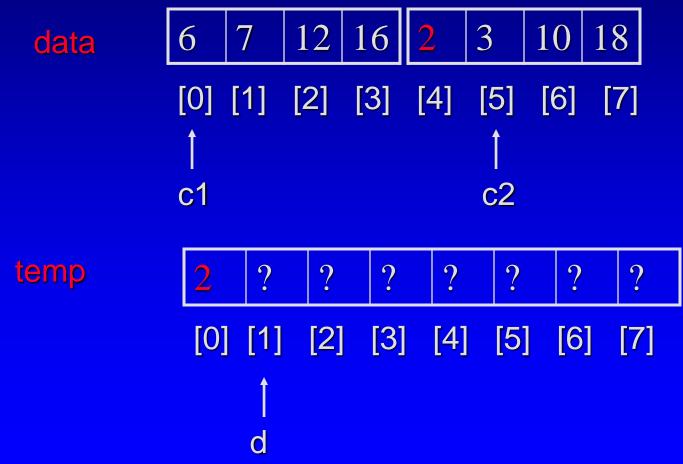


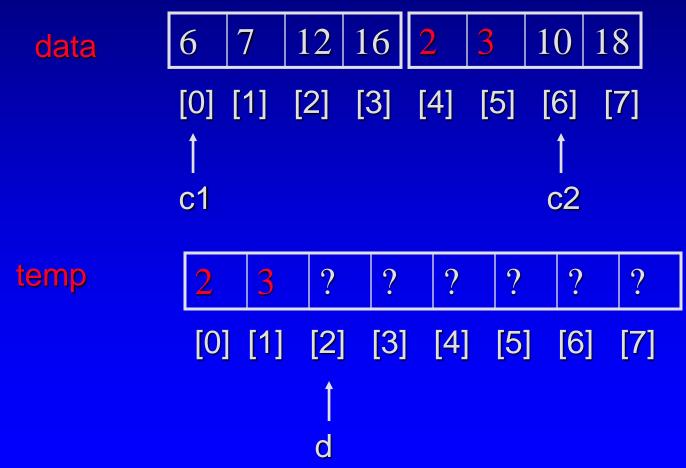


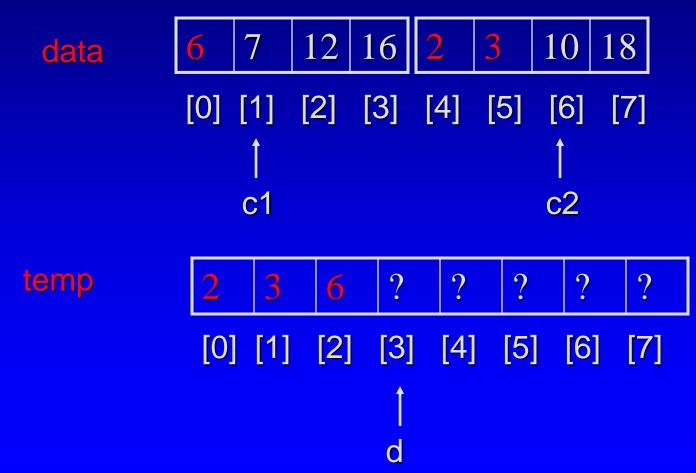
#### Mergesort – two issues

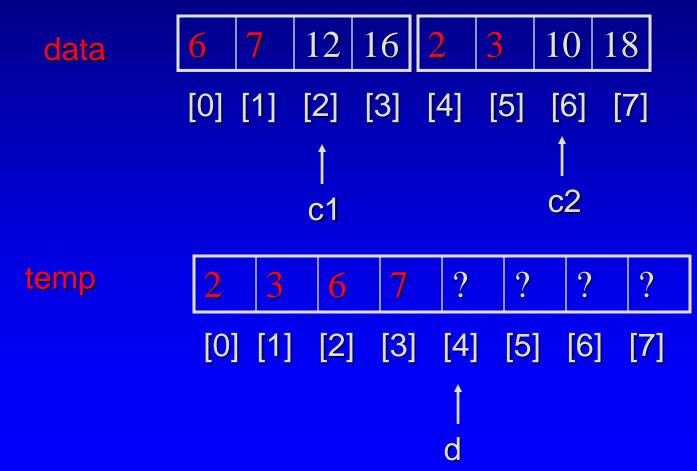
Specifying a subarray with pointer arithmetic  $\Box$  int data[10];  $\Box$  (data+i)[0] is the same as data[i]  $\Box$  (data+i][1] is the same as data[i+1] Merging two sorted subarrays into a sorted list □ need a temporary array (by new and then delete) □ step through the two sub-arrays with two cursors, and copy the elements in the right order

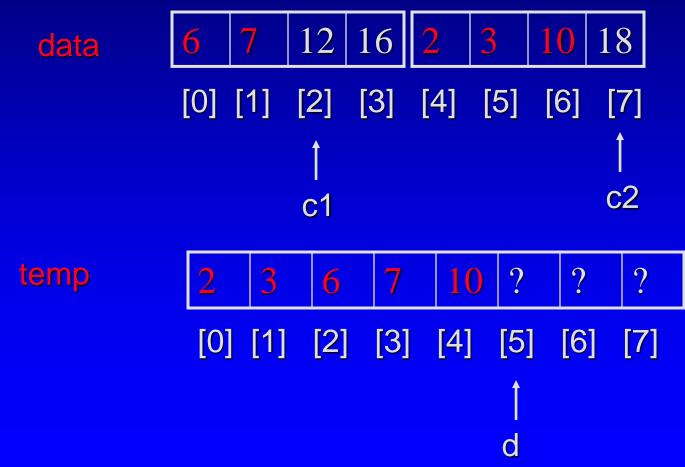


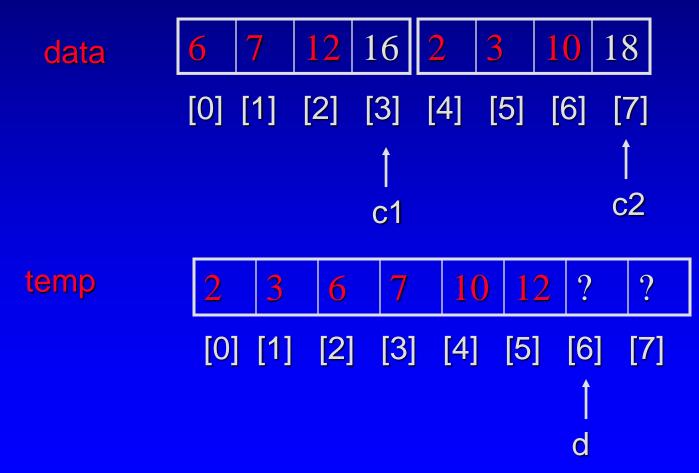


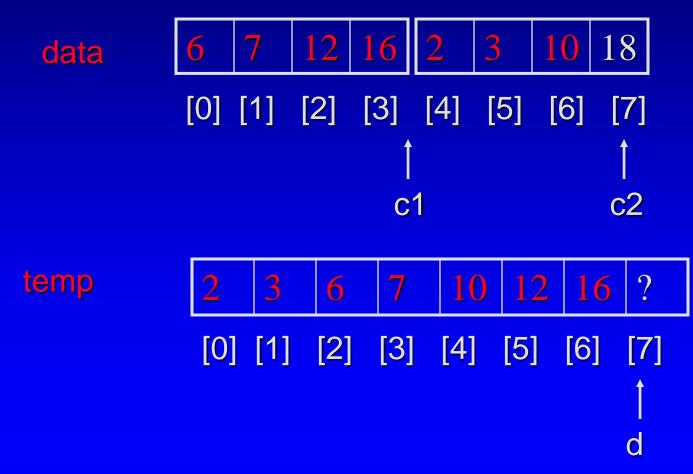


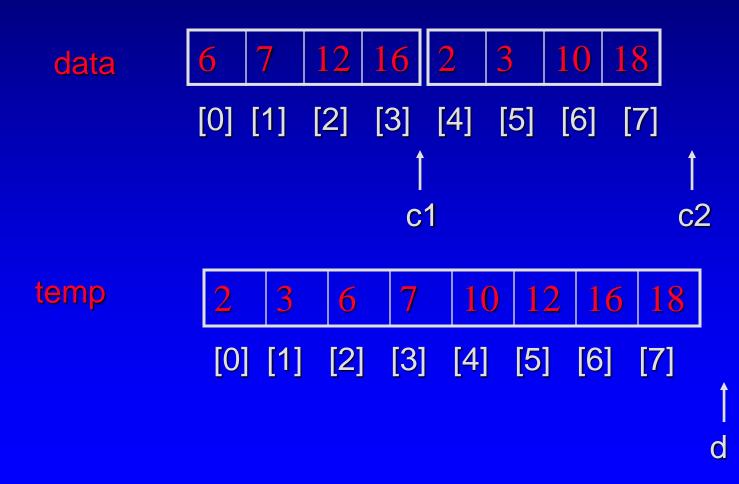


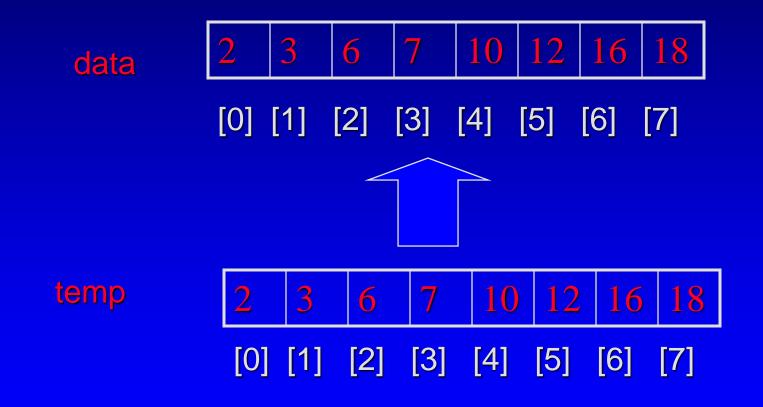














# Mergesort – Time Analysis

The worst-case running time, the averagecase running time and the best-case running time for mergesort are all O(n log n)



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# Mergesort – Time Analysis

- $\Box$  At the top (0) level, 1 call to merge creates an array with n elements
- $\Box$  At the 1<sup>st</sup> level, 2 calls to merge creates 2 arrays, each with n/2 elements
- $\Box$  At the 2<sup>nd</sup> level, 4 calls to merge creates 4 arrays, each with n/4 elements
- □ At the 3<sup>rd</sup> level, 8 calls to merge creates 8 arrays, each with n/8 elements
- $\Box$  At the *d*th level, 2<sup>*d*</sup> calls to merge creates 2<sup>*d*</sup> arrays, each with n/2<sup>*d*</sup> elements
- $\Box$  Each level does total work proportional to  $n \Rightarrow c n$ , where c is a constant
- Assume at the dth level, the size of the subarrays is  $n/2^d = 1$ , which means all the work is done at this level, therefore
  - $\Box \quad \text{the number of levels } d = \log_2 n$
- $\Box \quad \text{The total cost of the mergesort is } c nd = c n \log_2 n$ 
  - $\Box \quad \text{therefore the Big-O is } O(n \log_2 n)$

# Heapsort

Heapsort – Why a Heap? (two properties)
Heapsort – How to? (two steps)
Heapsort – How good? (time analysis)

# Heap Definition

A heap is a binary tree where the entries of the nodes can be compared with the *less than* operator of a strict weak ordering.
In addition, two rules are followed:

The entry contained by the node is NEVER *less than* the entries of the node's children
The tree is a COMPLETE tree.

# Why a Heap for Sorting?

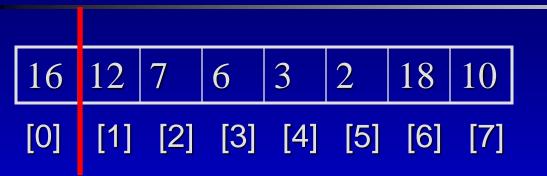
□ Two properties

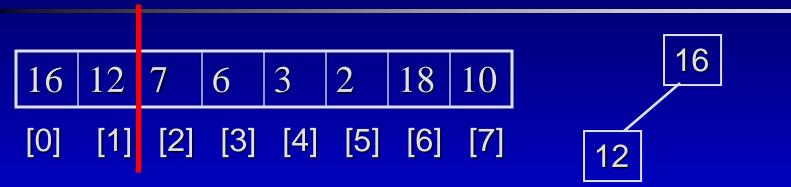
- □ The largest element is always at the root
- Adding and removing an entry from a heap is O(log n)

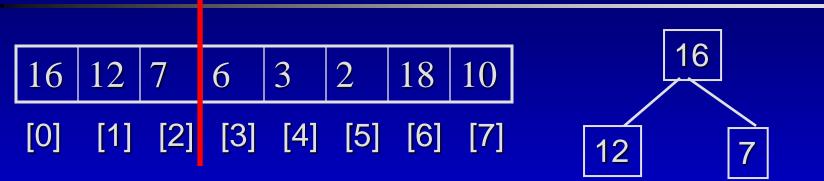
### Heapsort – Basic Idea

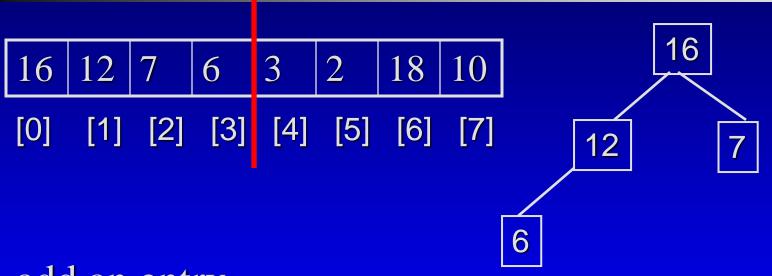
□ Step 1. Make a heap from elements □ add an entry to the heap one at a time  $\Box$  reheapification upward n times – O(n log n) □ Step 2. Make a sorted list from the heap Remove the root of the heap to a sorted list and Reheapification downward to re-organize into an updated heap  $\Box$  n times – O(n log n)

3 12 7 6 2 18 10 16 [2] [3] [4] [5] [6] [0] [1] [7]

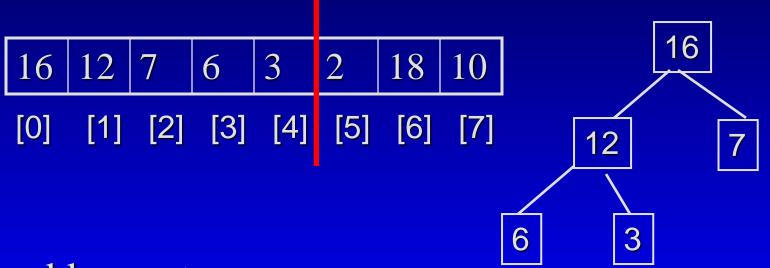




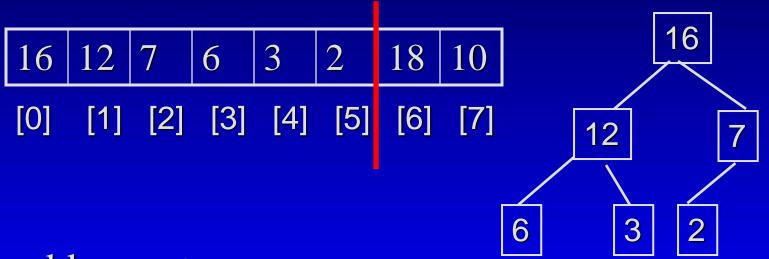




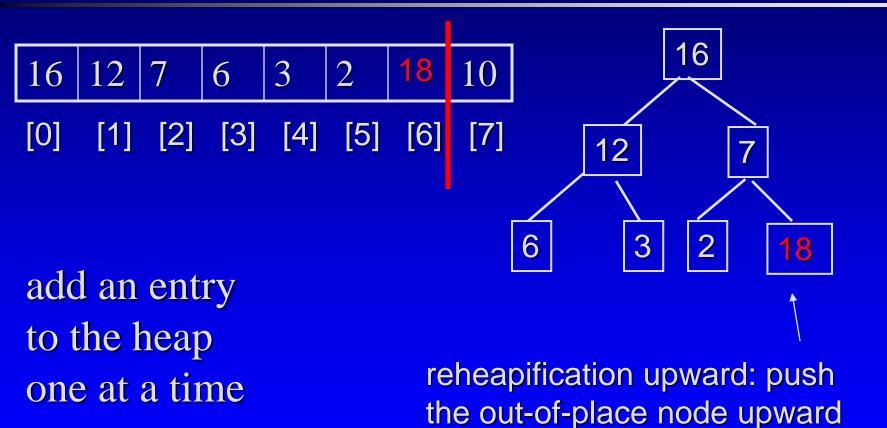
add an entry to the heap one at a time

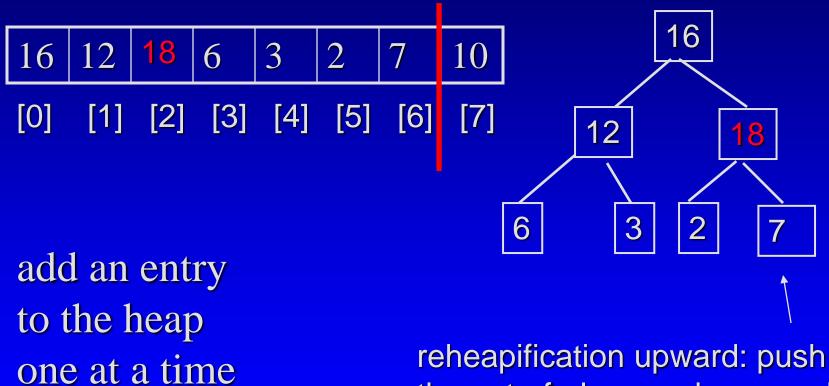


add an entry to the heap one at a time

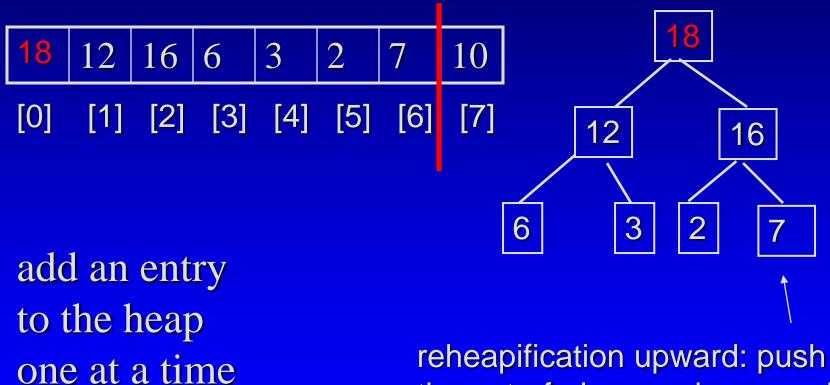


add an entry to the heap one at a time

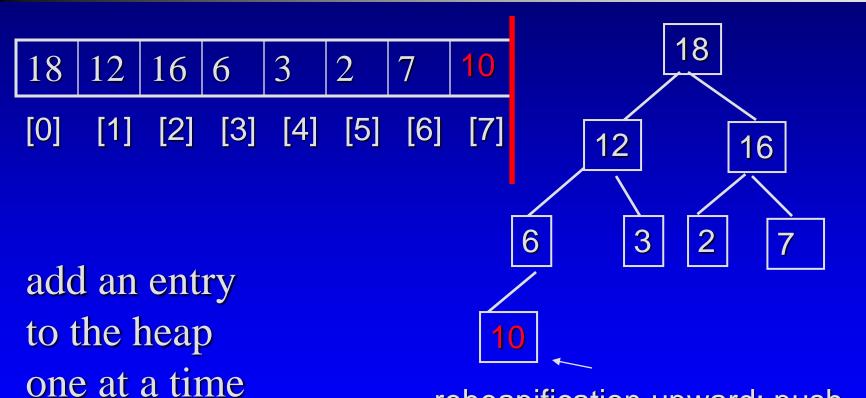




the out-of-place node upward



reheapification upward: push the out-of-place node upward until it is in the right place

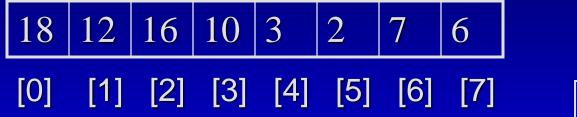


reheapification upward: push the out-of-place node upward until it is in the right place

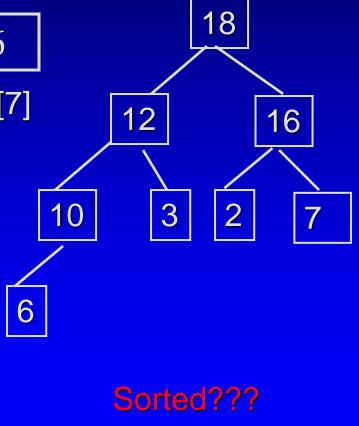
18 18 16 10 2 12 3 6 [0] [2] [4] [5] [6] [7] [3] [1] 12 16 10 3 2 add an entry to the heap 6

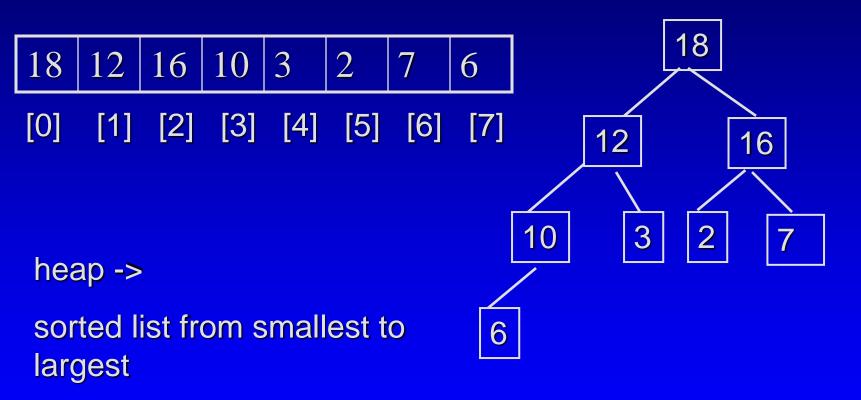
> reheapification upward: push the out-of-place node upward until it is in the right place

one at a time



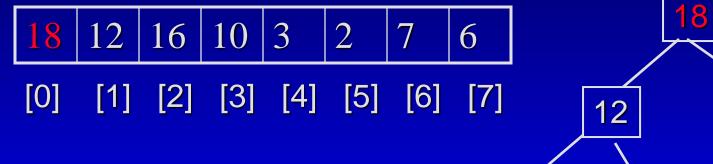
A heap is created: it is saved in the original array- the tree on the right is only for illustration!





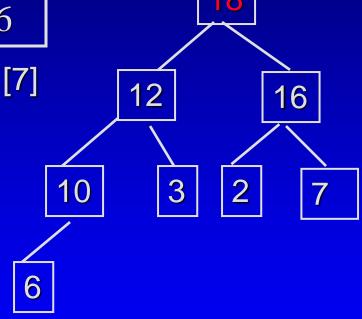
# Q: where is the largest entry?

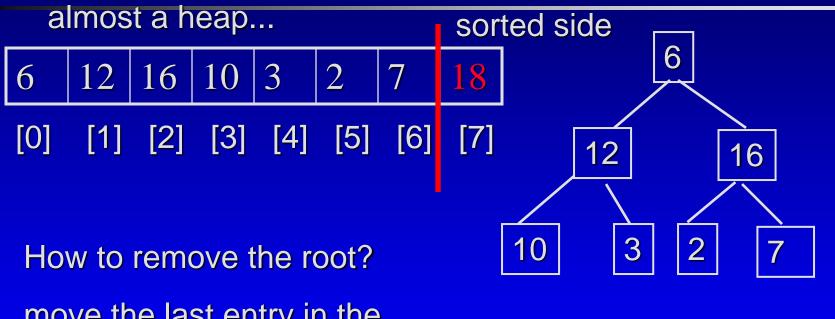
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Idea: remove the root of the heap and place it in the sorted list

=> recall: how to remove the root?

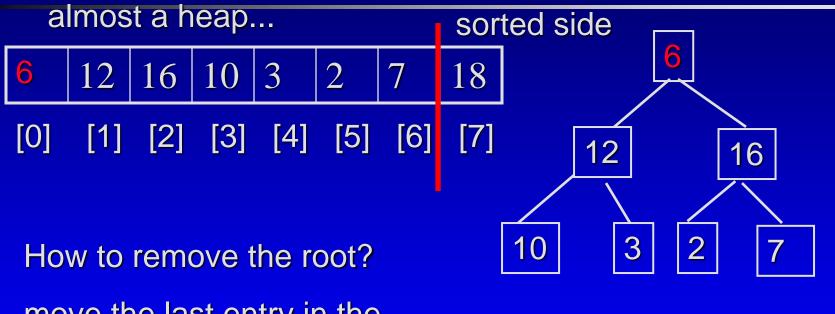




move the last entry in the root...

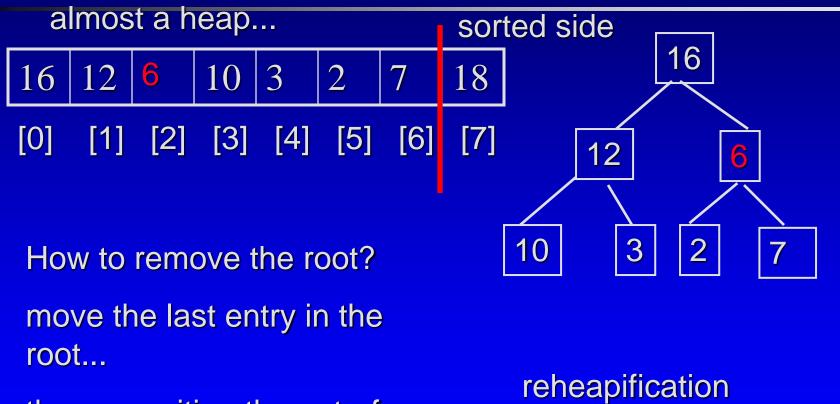
and for the sake of sorting, put the root entry in the "sorted side"

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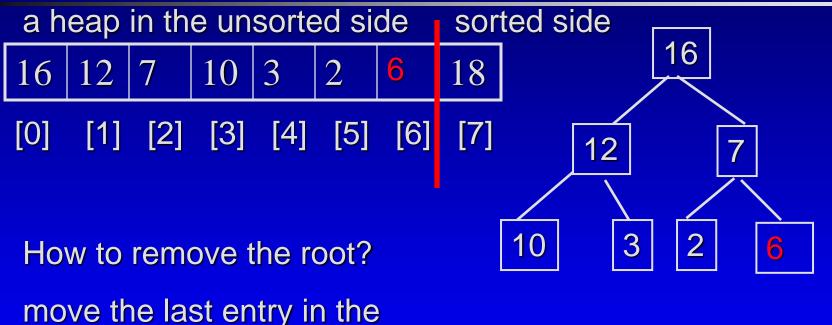


move the last entry in the root...

then reposition the out-of place node to update the heap @ George Wolberg, 2020

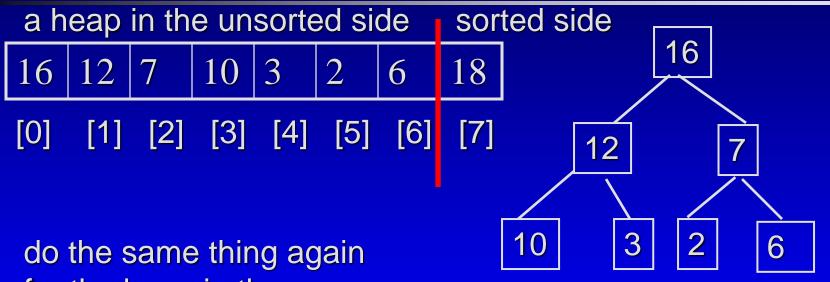


then reposition the out-of place node to update the heap @ George Wolberg, 2020 reheapification downward

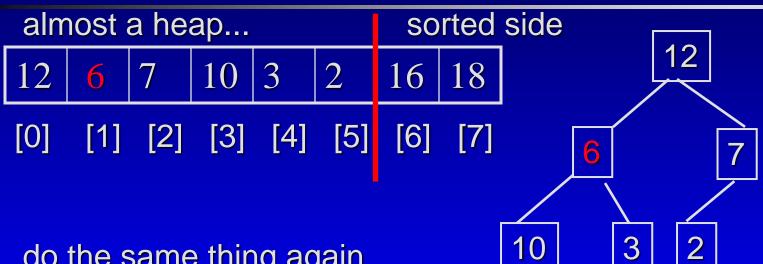


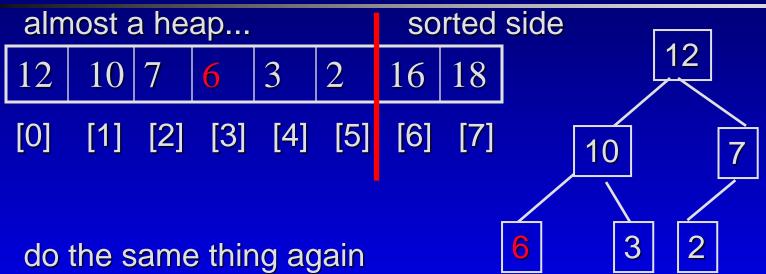
root...

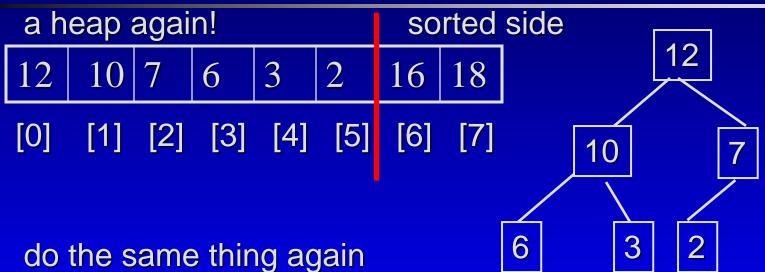
then reposition the out-of place node to update the heap @ George Wolberg, 2020 reheapification downward



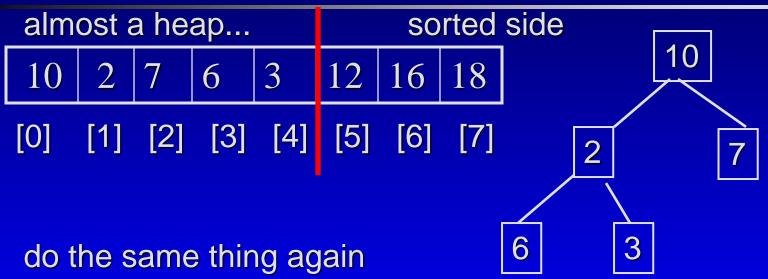


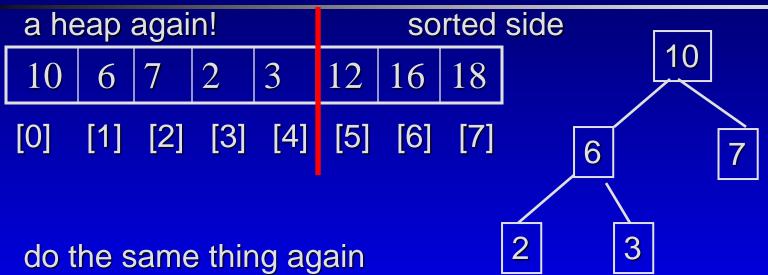


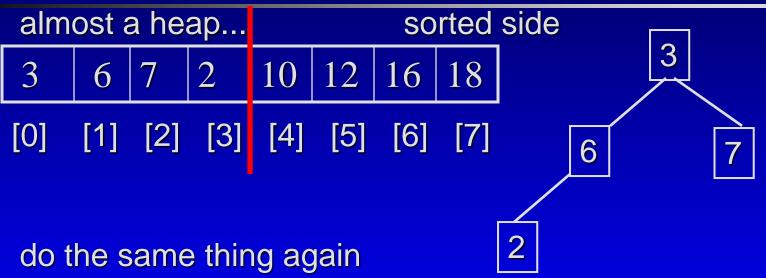


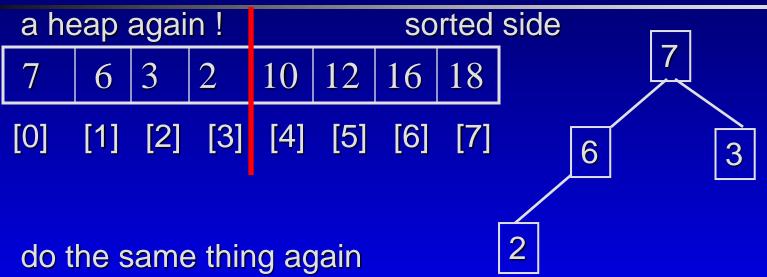


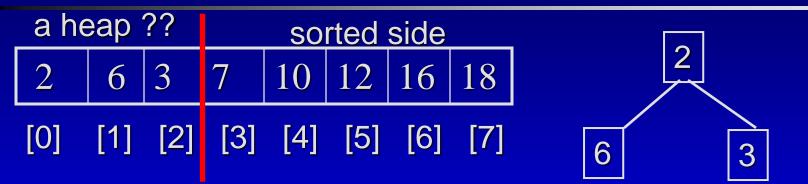


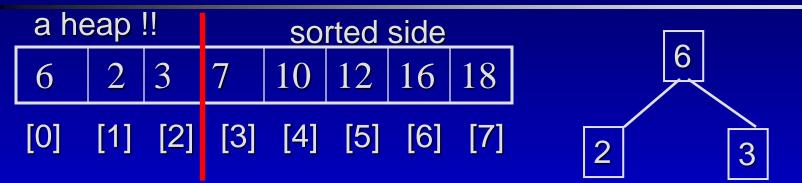


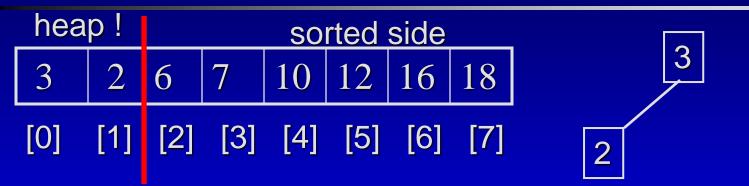












heap !				sorted side					
	2	3	6	7	10	12	16	18	
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	

2

 2
 3
 6
 7
 10
 12
 16
 18

 [0]
 [1]
 [2]
 [3]
 [4]
 [5]
 [6]
 [7]

do the same thing again for the heap in the unsorted side until all the entries have been moved to the sorted side **DONE!** 

#### Heapsort – Time Analysis

Step 1. Make a heap from elements add an entry to the heap one at a time  $\Box$  reheapification upward n times – O(n log n) Step 2. Make a sorted list from the heap Remove the root of the heap to a sorted list and □ Reheapification downward to re-organize the unsorted side into an updated heap  $\Box$  do this n times – O(n log n)

 $\Box$  The running time is O(n log n)

# C++ STL Sorting Functions

 $\Box$  The C++ sort function □ void sort(Iterator begin, Iterator end); □ The original C version of qsort void qsort( void \*base, size\_t number\_of\_elements, size\_t element\_size, int compare(const void\*, const void\*) );

## Summary & Homework

**Recursive Sorting Algorithms** Divide and Conquer technique □ An O(NlogN) Sorting Algorithm using a Heap □ making use of the heap properties STL Sorting Functions  $\Box$  C++ sort function Original C version of qsort □ Homework □ use your heap implementation to implement a heapsort!