



CSc 16716
Spring 2013

3D Computer Vision

Introduction

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- Basic Information:
 - Course participation
 - Books, notes, etc.
 - Web page – check often!
- Homework, Assignment, Exam
 - Homework and exams
 - Grading
- *Goal*
 - What I expect from you
 - What you can expect from me
 - Resources

- Textbook
 - Online lecture notes (in the form of book chapters) provided with the class
- Additional readings when necessary
 - “Computer Vision – A Modern Approach” Forsyth and Ponce, 2003
 - “Three-Dimensional Computer Vision: A Geometric Viewpoint” O. Faugeras, 1998
 - “Image Processing, Analysis and Machine Vision” Sonika, Hlavac and Boyle, 1999
 - “Introductory Techniques for 3-D Computer Vision” Trucco and Verri, 1998
- On-Line References

- Linear Algebra
- A little Probability and Statistics
- Programming Experience
- Reading Literature (A little)
- An Inquisitive Nature (Curiosity)
- No Fear

<http://www-cs.engr.cuny.cuny.edu/~zhu/CSCI6716-2013s/VisionCourse-Spring-2013.html>

- Lectures available in Powerpoint format
- All homework assignments will be distributed over the web
- Additional materials and pointers to other web sites
- Course bulletin board contains last minute items, changes to assignments, etc.
 - **CHECK IT OFTEN!**
 - You are responsible for material posted there

- Complete syllabus on the web pages (14 meets)
- Rough Outline (3D Computer Vision):
 - Part 1. Vision Basics** (Total 4)
 - 1. Introduction (1)
 - 2. Image Formation and Processing (1) (hw 1, matlab)
 - 3-4. Features and Feature Extraction (2) (hw 2)
 - Part 2. 3D Vision** (Total 7)
 - 5. Camera Models (1)
 - 6. Camera Calibration (2)(hw 3)
 - 7. Stereo Vision (2) (project assignments)
 - 8. Visual Motion (2) (hw 4)
 - Part 3. Exam and Projects** (Total 3)
 - 9. Midterm exam (1)
 - 10. Project and Exam discussions (0.5)
 - 11. Student Project presentations (1.5)

- Homework (4): 40%
- Exam (midterm): 40%
- Course Project + Presentation: 20%
 - Groups (2-3 students) for discussions
 - Experiments – independently + collaboratively
 - Written Report - independently + collaboratively
- All homework must be yours....but you can work together until the final submission

- **Teaching Assistant:**
 - Mr. Wai L. Khoo <WKhoo@gc.cuny.edu>

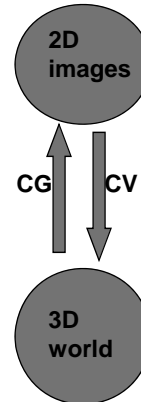
- C++
 - For some simple computation, you may use C++

- Matlab
 - An interactive environment for numerical computation
 - Available on Computer Labs machines (both Unix and Windows)
 - ◆ Matlab primer available on line (web page)
 - ◆ Pointers to on-line manuals also available
 - Good rapid prototyping environment

- Use C++ and/or Matlab for your homework assignments and project(s);
However Java will also be fine

■ What makes (3D) Computer Vision interesting ?

- Image Modeling/Analysis/Interpretation
 - ◆ Interpretation is an Artificial Intelligence Problem
 - Sources of Knowledge in Vision
 - Levels of Abstraction
 - ◆ Interpretation often goes from 2D images to 3D structures
 - since we live in a 3D world
- Image Rendering/Synthesis/Composition
 - ◆ Image Rendering is a Computer Graphics problem
 - ◆ Rendering is from 3D model to 2D images



- Image Processing: image to image
 - Computer Vision: Image to model
 - Computer Graphics: model to image
- All three are interrelated!**

- Pattern Recognition: image to class
 - image data mining/ video mining
 - Artificial Intelligence: machine smarts
 - Machine perception
- AI**

- Photogrammetry: camera geometry, 3D reconstruction
 - Medical Imaging: CAT, MRI, 3D reconstruction (2nd meaning)
 - Video Coding: encoding/decoding, compression, transmission
- Applications**

- Physics & Mathematics: basics
 - Neuroscience: wetware to concept
- basics**

- Computer Science: programming tools and skills?

■ ■ 3D Computer Vision
■ ■ and Video Computing **Applications**
■ ■

- Visual Inspection (*)
- Robotics (*)
- Intelligent Image Tools
- Image Compression (MPEG 1/2/4/7)
- Document Analysis (OCR)
- Image and Video on the Web
- Virtual Environment Construction (*)
- Environment (*)
- Media and Entertainment
- Medicine
- Astronomy
- Law Enforcement (*)
 - surveillance, security
- Traffic and Transportation (*)
- Tele-Conferencing and e-Learning (*)
- Human Computer Interaction (HCI)

■ ■ 3D Computer Vision
■ ■ and Video Computing **Job Markets**
■ ■

- Homeland Security
 - Port security – cargo inspection, human ID, biometrics
 - Facility security – Embassy, Power plant, bank
 - Surveillance – military or civilian
- Media Production
 - Cartoon / movie/ TVs/ photography
 - Multimedia communication, video conferencing
- Research in image, vision, graphics, virtual reality
 - 2D image processing
 - 3D modeling, virtual walk-through
- Consumer/ Medical Industries
 - Video cameras, Camcorders, Video phone
 - Medical imaging 2D -> 3D



- Image processing (mainly in 2D)
 - Image to Image transformations
 - Image to Description transformations
 - Image Analysis - extracting quantitative information from images:
 - ◆ Size of a tumor
 - ◆ distance between objects
 - ◆ facial expression
 - Image restoration. Try to undo damage
 - ◆ needs a model of how the damage was made
 - Image enhancement. Try to improve the quality of an image
 - Image compression. How to convey the most amount of information with the least amount of data



Vision is the art of seeing things invisible.

-Jonathan Swift (1667-1745)
"Thoughts on Various Subjects"
Miscellanies in Prose and Verse
(published with Alexander Pope),
vol. 1, 1727

- Computer vision systems attempt to construct meaningful and explicit descriptions of the world depicted in an image.
- Determining from an image or image sequence:
 - The objects present in the scene
 - The relationship between the scene and the observer
 - The structure of the three dimensional (3D) space



Directly Measurable in an Image

- Spectral Characteristics
 - Intensity, contrast, colors and their
 - Spatial distributions
- 2D Shape of Contours
- Linear Perspective
- Highlights and Shadows
- Occlusions
- Organization
- Motion parallax and Optical Flow
- Stereopsis and sensor convergence

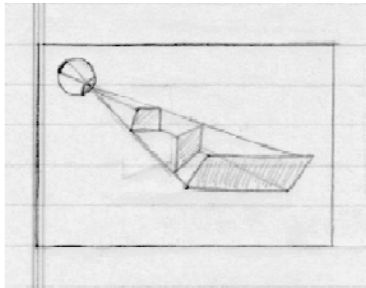


Inferred Properties

- Surface connectivity
- 3D Volume
- Hidden sides and parts
- Identity (Semantic category)
- Absolute Size
- Functional Properties
- Goals, Purposes, and Intents
- Organization
- Trajectories



- Question:
 - How do we perceive the three-dimensional properties of the world when the images on our retinas are only two-dimensional?
- Stereo is not the entire story!



- Monocular cues to the perception of depth in images
 - Interposition: occluding objects appear closer than occluded objects
 - Relative size: when objects have approximately the same physical size, the larger object appears closer
 - Relative height: objects lower in the image appear closer
 - Linear Perspective: objects appear smaller as they recede into the distance
 - ◆ texture gradients
 - Aerial Perspective: change in color and sharpness as object recede into the distance
 - Illumination gradients: gradients and shadow lend a sense of depth
 - Relative Motion: faster moving objects appear closer



■ Physiological cues to depth:

- Focus (accommodation): change in curvature of the lens for objects at different depths
- Convergence: eyes turn more inward (nasal) for closer objects
- Retinal disparity: greater for objects further away





3D Computer Vision
and Video Computing

Interposition



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Interposition



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Different viewpoint



3D Computer Vision
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Different viewpoint

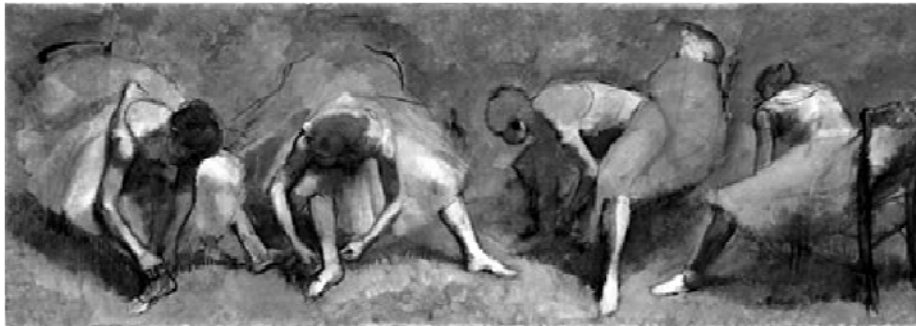


Edgar Degas: Dance Class at the Opéra, 1872

**Edgar Degas:
Green Dancer,
c.1880**



Edgar Degas: Frieze of Dancers, c.1895





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- Constable



- Classic Chinese Paintings

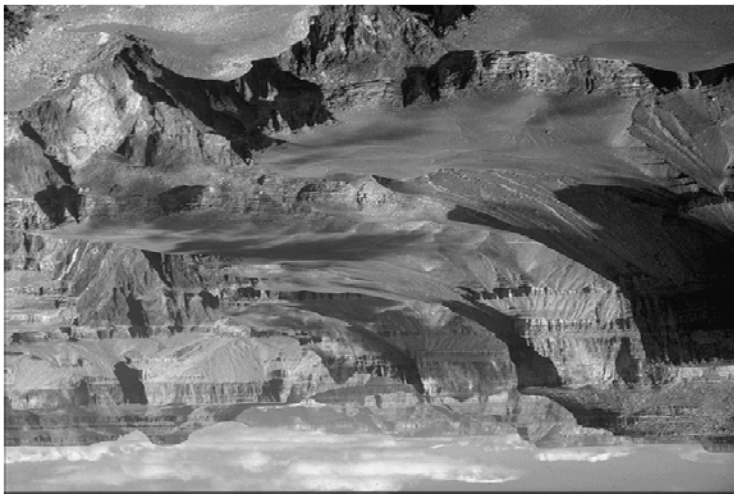




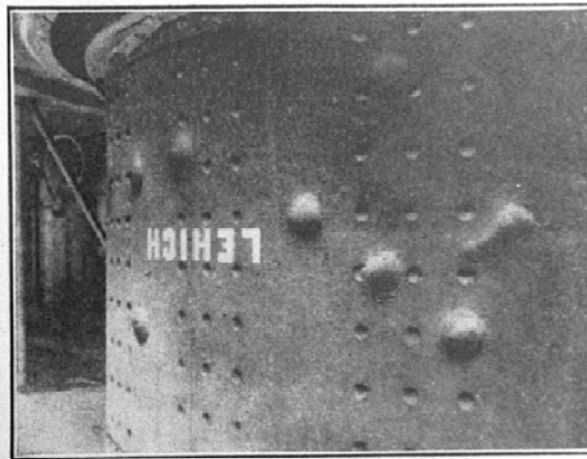
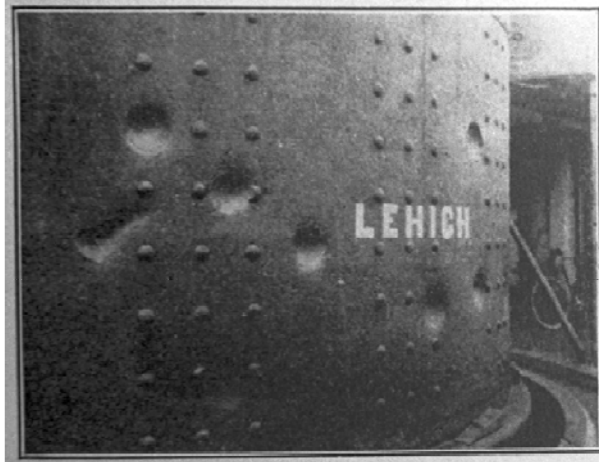


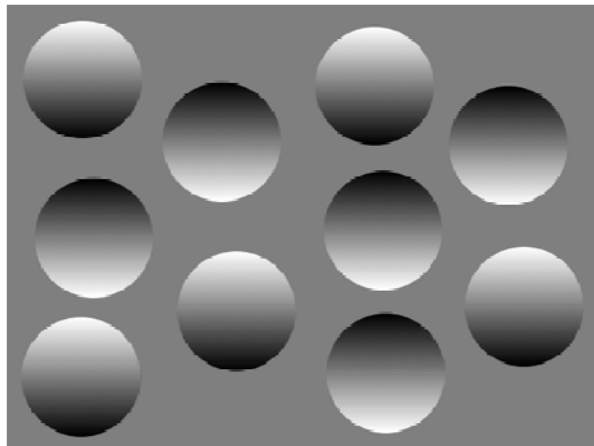
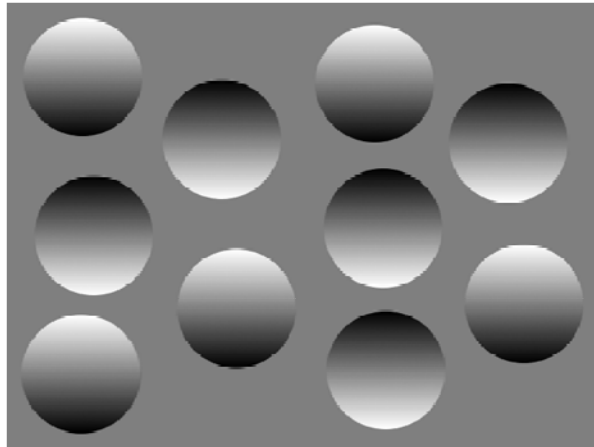


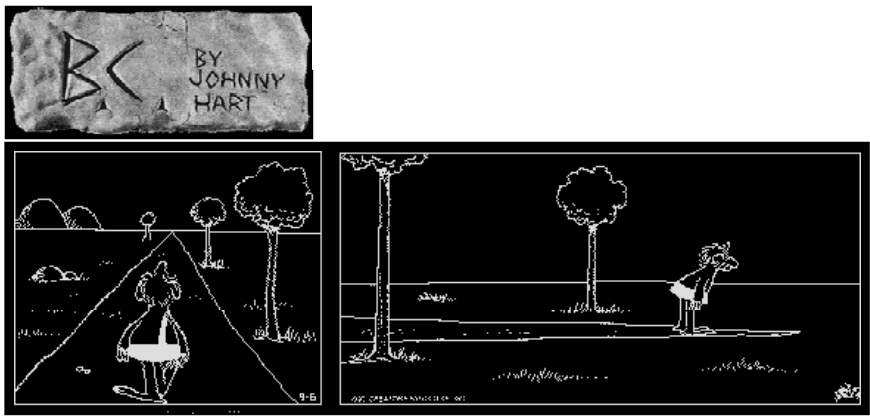
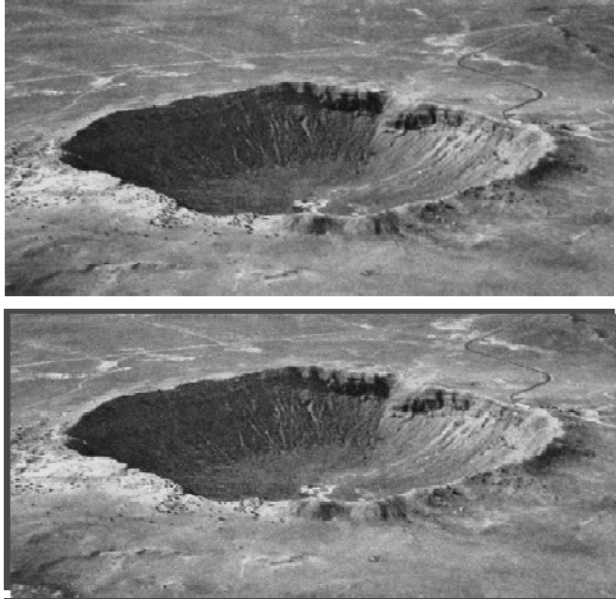




- C. H. Stoelting Company





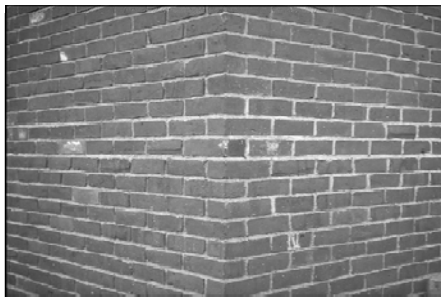




Sunflowers in Fargo, ND
Photo by Bruce Fitz

<http://www.ars.usda.gov/is/graphics/photos/>







**Anyone who isn't confused really doesn't
understand the situation.**

--Edward R. Murrow

**Next:
Image Formation**

